A proximal multiplier method for separable convex minimization

O. Sarmiento C.* E. A. Papa Quiroz† and P. R. Oliveira‡

Systems Engineering and Computer Science, COPPE, Federal University of Rio de Janeiro, postal address: 68511, CEP: 21941-972, Rio de Janeiro, Brazil.
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In this paper, we propose an inexact proximal multiplier method using proximal distances for solving convex minimization problems with a separable structure. The proposed method unified the work of Chen and Teboulle (PCPM method), Kyono and Fukushima (NPCPMM) and Auslender and Teboulle (EPDM) and extends the convergence properties for the class of $\varphi$–divergence distances. We prove, under standard assumptions, that the iterations generated by the method are well defined and the sequence converges to an optimal solution of the problem.

Keywords: Proximal multiplier methods; separable convex problems; proximal distances; convex functions.

AMS Subject Classification:

1. Introduction

In this paper, we are interested in solving the following separable convex optimization problem:

$$(CP) \quad \min \{ f(x) + g(z) : Ax + Bz = b, \ x \in \bar{C}, \ z \in \bar{K} \},$$

where $C \subset \mathbb{R}^n$ and $K \subset \mathbb{R}^p$ are nonempty open convex sets, $\bar{C}$ and $\bar{K}$ denote the closure (in the euclidean topology) of $C$ and $K$ respectively, $f : \mathbb{R}^n \to (-\infty, +\infty]$ and $g : \mathbb{R}^p \to (-\infty, +\infty]$ are closed proper convex functions and $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{m \times p}$, $b \in \mathbb{R}^m$.

The Fenchel dual problem, see [22], for (CP) is defined as:

$$(D) \quad \max \{ -(f + \delta_{\bar{C}})^*( -A^T y ) - (g + \delta_{\bar{K}})^* ( -B^T y ) - \langle y, b \rangle : y \in \mathbb{R}^m \}$$

where $\delta_X$ denotes the indicator function of a subset $X$, $(f + \delta_{\bar{C}})^*$, $(g + \delta_{\bar{K}})^*$ are the conjugate functions of $f + \delta_{\bar{C}}$ and $g + \delta_{\bar{K}}$, respectively, and $\langle \cdot, \cdot \rangle$ denotes the canonical inner product.

The Lagrangian for (CP) is defined by $L : \mathbb{R}^n \times \mathbb{R}^p \times \mathbb{R}^m \to (-\infty, +\infty]$, $L(x, z, y) = (f + \delta_{\bar{C}})(x) + (g + \delta_{\bar{K}})(z) + \langle y, Ax + Bz - b \rangle$. 

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*Email: osarmiento@cos.ufrj.br
†Corresponding author. Email: erikpapa@gmail.com
‡Email: poliveir@cos.ufrj.br
where $y$ is the Lagrangian multiplier associated with the constraint $Ax + Bz = b$. Let $(x^*, z^*) \in \mathbb{R}^n \times \mathbb{R}^p$ and $y^* \in \mathbb{R}^m$. In order that $(x^*, z^*)$ be an optimal solution of (CP) and $y^*$ be an optimal Lagrangian multiplier, it is necessary and sufficient that $(x^*, z^*, y^*)$ be a saddle point of the Lagrangian $L$ of (CP) (see [22], Theorem 28.3); i.e., for all $x \in \text{dom } f \cap \mathcal{C}$, $z \in \text{dom } g \cap \mathcal{K}$ and $y \in \mathbb{R}^m$, we have

$$L(x^*, z^*, y) \leq L(x^*, z^*, y^*) \leq L(x, y^*).$$

In recent decades a great interest has emerged in studying the separable structure of the problem (CP), this model has been found in various optimization problems, for example in telecommunications, see Mahey et. al. [20], management electricity, see Lenoir [17], and in computer science to solve matrix completion problems, see example 2 of Goldfarb et. al. [14].

Classical methods for solving (CP) based on the proximal point algorithm (PPA) are the method of multipliers, [6], which is obtained by applying the PPA to the dual problem (D), and the proximal method of multipliers [23], which is obtained by applying the PPA to the primal-dual problem. However, these algorithms do not take full advantage of the separable structure of the original problem (CP).

Various decomposition methods that exploit the special structure of the problem have been proposed. Some examples of such methods are: alternating directions method of multipliers [7, 11, 12, 18], partial inverse of Spingarn method [10, 19, 20, 24, 25], predictor corrector proximal multipliers methods of Chen and Teboulle and its extensions [3, 9, 16].

For the particular case when $\mathcal{C} = \mathbb{R}^n$, $\mathcal{K} = \mathbb{R}^m$, $B = -I$ and $b = 0$ in (CP), the exact version of Chen and Teboulle [9], called Predictor-Corrector Proximal Multiplier (PCPM) method, given an initial point $(x^0, z^0, y^0)$, generates a sequence of points $\{(x^k, z^k, y^k)\}$ with the following iterative scheme:

$$p^{k+1} = y^k + \lambda_k(Ax^k - z^k)$$

$$x^{k+1} = \arg\min \left\{ f(x) + \langle y^{k+1}, Ax \rangle + (1/2\lambda_k)\|x - x^k\|^2 \right\}$$

$$z^{k+1} = \arg\min \left\{ g(z) - \langle p^{k+1}, z \rangle + (1/2\lambda_k)\|z - z^k\|^2 \right\}$$

$$y^{k+1} = y^k + \lambda_k(Ax^{k+1} - z^{k+1})$$

where $\lambda_k$ is a positive parameter. Assuming that there exists an optimal primal-dual solution $(x^*, z^*, y^*)$, Chen and Teboulle [9] proved that the sequence $\{(x^k, z^k, y^k)\}$ globally converges to $(x^*, z^*, y^*)$, that is, converges to a primal and dual solution respectively. Furthermore, they proved a linear rate of convergence of the (PCPM) method.

Kyono and Fukushima [16], studied the same particular problem, the exact version of their algorithm, called Nonlinear Predictor-Corrector Proximal Multiplier Method (NPCPMM), substitute (2) and (3) by the following iterations:

$$x^{k+1} = \arg\min \left\{ f(x) + \langle y^{k+1}, Ax \rangle + (1/\lambda_k)D_h(x, x^k) \right\}$$

$$z^{k+1} = \arg\min \left\{ g(z) - \langle y^{k+1}, z \rangle + (1/\lambda_k)D_h(z, z^k) \right\}$$

where $D_h$ is a Bregman distance. An advantage of this method over the (PCPM) algorithm is that, by a suitable choice of the Bregman distance, each subproblem
becomes in an unconstrained problem. Under similar assumptions that Chen and Teboulle, the authors have been proved the global convergence of the iterations to a primal and dual solution respectively.

Independently to the work of Kyono and Fukushima [16], Auslender and Teboulle [3], studied convex optimization and variational inequality problems with a separable structure. For the optimization case, they considered the problem (CP) with $\mathcal{C} = \mathbb{R}_+^n$ and $\mathcal{K} = \mathbb{R}_+^m$. The authors, motivated by the earlier work of Auslender, Teboulle and Ben-Tiba [2], substituted the iteration (2) by:

$$x^{k+1} = \arg \min \left\{ f(x) + \langle p^{k+1}, Ax \rangle + (1/\lambda_k) d(x, x^k) \right\}$$

where

$$d(u, v) = \begin{cases} \sum_{i=1}^n \frac{\sigma_i}{2} (u_i - v_i)^2 + \mu (v_i^2 \log(\frac{v_i}{u_i}) + u_i v_i - v_i^2), & \text{if } u \in \mathbb{R}_+^n \\
\infty, & \text{otherwise} \end{cases}$$

Under the same above assumption they proved the global convergence of the iterations to a primal and dual solution respectively.

In this paper, we consider the general problem (CP) and propose the following inexact iteration: Given $(x^k, z^k, y^k) \in \mathcal{C} \times \mathcal{K} \times \mathbb{R}^m$, find $(x^{k+1}, v^{k+1}) \in \mathcal{C} \times \mathbb{R}^n$ and $(z^{k+1}, \xi^{k+1}) \in \mathcal{K} \times \mathbb{R}^p$ such that

$$p^{k+1} = y^k + \lambda_k (Az^k + Bz^k - b)$$
$$v^{k+1} \in \partial_{\lambda_k} f^k(x^{k+1}), \quad v^{k+1} + \lambda_k^{-1} \nabla_1 d(x^{k+1}, x^k) = 0,$$
$$\xi^{k+1} \in \partial_{\lambda_k} g^k(z^{k+1}), \quad \xi^{k+1} + \lambda_k^{-1} \nabla_1 d'(z^{k+1}, z^k) = 0,$$
$$y^{k+1} = y^k + \lambda_k (Ax^{k+1} + Bz^{k+1} - b)$$

where the functions $f^k : \mathbb{R}^n \to (-\infty, +\infty]$ and $g^k : \mathbb{R}^p \to (-\infty, +\infty]$ are defined by $f^k(x) = f(x) + \langle p^{k+1}, Ax \rangle$ and $g^k(z) = g(z) + \langle p^{k+1}, Bz \rangle$, respectively, with $p^{k+1}$ as above, $\partial_{\lambda_k} f^k$ and $\partial_{\lambda_k} g^k$ are the $\lambda_k$- and $b_k$-Fenchel subdifferential of $f^k$ and $g^k$ respectively, and $d, d'$ are regularized proximal distances, see sections 3 and 4.

This method is an extension of the (PCPM) and (NPCPMM) methods and includes the class of $\varphi$-divergence distances, see Subsection 3.3 of [5], what to our knowledge, not yet been studied in this context. Observe also that the (EPDM) is a particular case of the our method when in our algorithm we consider exact iterations and we use the regularized log-quadratic distance, see Section 2 of [3]. Thus, the main result of this paper is show that the global convergence of the proposed method is still valid when we use regularized proximal distances.

The paper is organized as follows: In Section 2 we give some results in convex analysis. In Section 3 we present the class of proximal distances that we will use along the paper. In Section 4 we introduce the Proximal Multiplier Algorithm with Proximal Distances (PMAPD) and under some appropriate assumptions we prove the global convergence of the iterations to the solution of the (CP). Finally we present our conclusions and give some directions for future research.

2. Notations and some results in convex analysis

Throughout the paper $\mathbb{R}^n$ is the Euclidean space endowed with the canonical
inner product $(\cdot, \cdot)$ and the norm of $x$ given by $\|x\| := \langle x, x \rangle^{1/2}$. For a matrix $M \in \mathbb{R}^{m \times n}$ we define $\|M\| := \max_{\|x\| \leq 1} \|Mx\|$. Given an extended real valued function $f : \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\}$ we denote its domain by $\text{dom} f := \{x \in \mathbb{R}^n : f(x) < +\infty\}$ and its epigraph $\text{epi} f := \{(x, \beta) \in \mathbb{R}^n \times \mathbb{R} : f(x) \leq \beta\}$. $f$ is said to be proper, if $\text{dom} f \neq \emptyset$ and for all $x \in \text{dom} f$, we have $f(x) \geq -\infty$. Also denote by $\text{ri}(X)$ the relative interior set of $X \subset \mathbb{R}^n$ and $\partial f$ is the $\epsilon-$subdifferential of $f$ defined by

$$\partial_\epsilon f(u) = \{p \in \mathbb{R}^n : f(v) \geq f(u) + \langle p, v - u \rangle - \epsilon, \forall v \in \text{dom} f\}.$$ 

Finally, $f$ is a lower semicontinuous function if for each $x \in \mathbb{R}^n$ we have that all $\{x^l\}$ such that $\lim_{l \to +\infty} x^l = x$ implies that $f(x) \leq \liminf_{l \to +\infty} f(x^l)$. It is easy to prove that the lower semicontinuity of $f$ is equivalent to the closedness of the lower level set $L_f(\alpha) = \{x \in \mathbb{R}^n : f(x) \leq \alpha\}$, for each $\alpha \in \mathbb{R}$.

**Definition 1** Let $C$ be a nonempty convex set, the recession cone of $C$ is defined by

$$0^+(C) = \{z \in \mathbb{R}^n : w + tz \in C, \forall w \in C, t \geq 0\},$$

furthermore, we define the the recession function $f0^+ : \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\}$ such that $\text{epi}(f0^+) = 0^+ (\text{epi} f)$

**Definition 2** Let $f : \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\}$ be a proper function, the conjugate of $f$, denoted by $f^*$, is defined by

$$f^*(x^*) = \sup_x [(x, x^*) - f(x)].$$

**Proposition 2.1** ([22], Corollary 13.3.4, (c)) Let $f : \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\}$ be a closed proper convex function. Let $x^*$ be a fixed vector and let $g(x) = f(x) - \langle x, x^* \rangle$. Then, $x^* \in \text{int}(\text{dom} f^*)$ if and only if $(g0^+)(y) > 0$ for every $y \neq 0$.

**Proposition 2.2** ([22], Theorem 27.1, (d)) Let $f : \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\}$ be a closed proper convex function. The minimum set of $f$ is a non-empty and bounded set if and only if $0 \in \text{int}(\text{dom} f^*)$.

**Proposition 2.3** ([22], Theorem 9.3) Let $f_1, \ldots, f_m$ be proper convex functions on $\mathbb{R}^n$. If every $f_i$ is closed and $f_1 + \cdots + f_m$ is not identically $\pm \infty$, then $f_1 + \cdots + f_m$ is a closed proper convex function and

$$(f_1 + \cdots + f_m)0^+ = f_10^+ + \cdots + f_m0^+.$$

**Proposition 2.4** ([22], Theorem 8.5) Let $f : \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\}$ be a proper convex function. The recession function $f0^+$ of $f$ is then a positively homogeneous proper convex function. For every vector $y$, one has

$$(f0^+)(y) = \sup \{f(x + y) - f(x) : x \in \text{dom} f\}.$$ 

If $f$ is closed, $f0^+$ is closed too, and for any $x \in \text{dom} f$, $f0^+$ is given by the formula:

$$(f0^+)(y) = \sup_{\lambda > 0} \frac{f(x + \lambda y) - f(x)}{\lambda} = \lim_{\lambda \to +\infty} \frac{f(x + \lambda y) - f(x)}{\lambda}.$$
∀d the induced proximal distance to of our algorithm.

4 Given Definition on y, d, H

Finally, we write (C) iteration of the proximal method to stay in by definition d

We denote by (Ii) (ii) (iii) (iv) the gradient map of the function d

guarantee the existence of the proximal iterations. For each (C)

we have

We also denote (C) with respect to an open nonempty convex set (C)

Definition induced proximal distance, introduced by Auslender and Teboulle [5].

In this section, we present a variant of the definition of the proximal distance and

Proposition 2.5 ([22], Theorem 23.8) Let f₁, . . . , fₘ be proper convex functions

on $\mathbb{R}^n$ and let $f = f₁ + \cdots + fₘ$. If the convex sets $ri(dom fᵢ)$, $i = 1, 2, \ldots, m$ have

a point in common, then

$$\partial f(x) = \partial f₁(x) + \cdots + \partial fₘ(x), \ \forall x.$$  

3. Proximal Distances

In this section, we present a variant of the definition of the proximal distance and

induced proximal distance, introduced by Auslender and Teboulle [5].

Definition 3 A function $d : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}_+ \cup \{+\infty\}$ is called proximal distance

with respect to an open nonempty convex set $C \subset \mathbb{R}^n$ if for each $y \in C$ it satisfies

the following properties:

(i) $d(\cdot, y)$ is proper, lower semicontinuous, convex and continuously differentiable

on $C$;

(ii) $dom d(\cdot, y) \subset C$ and $dom \partial d(\cdot, y) = C$, where $\partial d(\cdot, y)$ denotes the classical

subgradient map of the function $d(\cdot, y)$ with respect to the first variable;

(iii) $d(\cdot, y)$ is coercive on $\mathbb{R}^n$ (i.e., $\lim_{||u|| \to \infty} d(u, y) = +\infty$).

(iv) $d(y, y) = 0$.

We denote by $D(C)$ the family of functions satisfying this definition.

Property (i) is needed to preserve convexity of $d(\cdot, y)$, property (ii) will force the

iteration of the proximal method to stay in $C$, and property (iii) will be used to

guarantee the existence of the proximal iterations. For each $y \in C$, $\nabla₁ d(\cdot, y)$ denote the gradient map of the function $d(\cdot, y)$ with respect to the first variable. Note that

by definition $d(\cdot, \cdot) \geq 0$ and from (iv) the global minimum of $d(\cdot, y)$ is obtained at

$y$, which shows that $\nabla₁ d(y, y) = 0$.

Definition 4 Given $d \in D(C)$, a function $H : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}_+ \cup \{+\infty\}$ is called the induced proximal distance to $d$ if there exists $\gamma \in (0, 1]$ with $H$ a finite valued

on $C \times C$ and such that for each $a, b \in C$, we have

\begin{align*}
(Ii) \quad & H(a, a) = 0. \\
(Iii) \quad & ⟨c - b, \nabla₁ d(b, a)⟩ \leq H(c, a) - H(c, b) - \gamma H(b, a), \quad \forall c \in C.
\end{align*}

We write $(d, H) \in F(C)$ to the proximal and induced proximal distance that

satisfies the premises of Definition 4.

We also denote $(d, H) \in F(C)$ if there exists $H$ such that:

(Iiii) $H$ is finite valued on $\bar{C} \times C$ satisfying (Ii) and (Iiii), for each $c \in \bar{C}$.

(Iiv) For each $c \in \bar{C}$, $H(c, \cdot)$ has level bounded sets on $C$.

Finally, we write $(d, H) \in F(+C)$ if

\begin{align*}
(Iv) \quad & (d, H) \in F(C) . \\
(Ivi) \quad & \forall y \in \bar{C} \text{ and } \forall \{y^k\} \subset C \text{ bounded with } \lim_{k \to +\infty} H(y, y^k) = 0, \text{ we have } \\
(Ivii) \quad & \lim_{k \to +\infty} y^k = y. \\
(Iviii) \quad & \forall y \in \bar{C}, \text{ and } \forall \{y^k\} \subset C \text{ such that } \lim_{k \to +\infty} y^k = y, \text{ we obtain } \\
& \lim_{k \to +\infty} H(y, y^k) = 0.
\end{align*}

The following additional conditions on $H$ will be useful to prove the convergence of our algorithm.
Given \((d, H) \in \mathcal{F}_+ (\mathbb{C})\), \(H\) satisfies the following condition:

(iviii) For all \(c \in \mathbb{C}\), and for all \(\{y^k\} \subset \mathbb{C}\) such that \(\lim_{k \to +\infty} y^k = y\), then
\[
\lim_{k \to +\infty} H(c, y^k) = H(c, y).
\]

Some examples of proximal distances that satisfied (ii)-(iviii) are the following:

(a) **Bregman distances.** Let \(S \subseteq \mathbb{R}^n\) be a nonempty open convex set, and let \(\bar{S}\) be its closure. Let \(h : \bar{S} \to \mathbb{R} \cup \{+\infty\}\) be a proper, lower semicontinuous and convex function with \(\text{dom} \nabla h = S\), strictly convex and continuous on \(\text{dom} h\), and continuously differentiable on \(S\). Define
\[
H(x, y) := D_h(x, y) := h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \quad \forall x \in \bar{S}, \forall y \in S
\]
\[
= +\infty \quad \text{otherwise}.
\]

The function \(D_h\) enjoys a remarkable three point identity (see [8], Lemma 3.1),
\[
H(c, a) = H(c, b) + H(b, a) + \langle c - b, \nabla_1 H(b, a) \rangle \quad \forall a, b \in S, \forall c \in \text{dom} h.
\]

The function \(h\) is called a Bregman function with zone \(S\), if it satisfies the following conditions:

\[(B_1)\] \(\text{dom} h = \bar{S};\)
\[(B_2)\] \((i)\) \(\forall x \in \bar{S}, \ D_h(x, \cdot)\) is level bounded on \(\text{int}(\text{dom} h)\);
\((ii)\) \(\forall y \in S, \ D_h(\cdot, y)\) is level bounded;
\[(B_3)\] \(\forall y \in \text{dom} h\) and \(\forall \{y^k\} \subset \text{int}(\text{dom} h)\) with \(\lim_{k \to +\infty} y^k = y\), one has \(\lim_{k \to +\infty} D_h(y, y^k) = 0;\)
\[(B_4)\] If \(\{y^k\}\) is a bounded sequence in \(\text{int}(\text{dom} h)\) and \(y \in \text{dom} h\) such that \(\lim_{k \to +\infty} D_h(y, y^k) = 0\), then \(\lim_{k \to +\infty} y^k = y.\)

Note that \((B_4)\) is a direct consequence of the first three properties, a fact proved by Kiwiel in ([15], Lemma 2.16).

Recall that a Bregman function \(h\) with zone \(S\) is said to be essentially smooth (see [22]) if it satisfies the following condition:

\[(B_5)\] If \(\{y^k\} \subset S\) is convergent to a point on the boundary of \(S\) and \(u \in S\), then \(\lim_{k \to +\infty} D_h(u, y^k) = +\infty.\)

Now, we show that this condition implies (iviii) for \(H = D_h\). Indeed, it is clear that, for \(\mathbb{C} = S\) defining
\[
d(x, y) := H(x, y) := D_h(x, y),
\]
we obtain that \((d, H) \in \mathcal{F}_+ (\mathbb{C})\). Now, we will verify that when \(h\) is a essentially smooth Bregman function, \(H\) satisfies the condition (iviii). Indeed, let \(c \in \mathbb{C}\) and a sequence \(\{y^k\} \subset \mathbb{C}\) such that \(\lim_{k \to +\infty} y^k = y\). Suppose that \(y\) is a point of the boundary of \(\mathbb{C}\), then from condition (ivii), we obtain
\[
\lim_{k \to +\infty} D_h(y, y^k) = 0. \quad (5)
\]

On the other hand, defining \(u = y^k + (1 - \theta)(y - y^k)\) with \(0 < \theta < 1\), clearly,
For $u \in \mathcal{C}$. Since $\nabla h$ is monotone, 
\[
\langle \nabla h(u), u - y^k \rangle \geq \langle \nabla h(y^k), u - y^k \rangle.
\]

Taking into account that $u - y^k = (1 - \theta)(y - y^k)$, the latter relation yields 
\[
\langle \nabla h(u), y - y^k \rangle \geq \langle \nabla h(y^k), y - y^k \rangle.
\]

Then 
\[
D_h(y, u) + D_h(u, y^k) = h(y) - h(u) - \langle \nabla h(u), y - u \rangle 
+ h(u) - h(y^k) - \langle \nabla h(y^k), u - y^k \rangle 
= h(y) - h(y^k) - \theta \langle \nabla h(u), y - y^k \rangle - (1 - \theta) \langle \nabla h(y^k), y - y^k \rangle 
\leq h(y) - h(y^k) - \theta \langle \nabla h(y^k), y - y^k \rangle - (1 - \theta) \langle \nabla h(y^k), y - y^k \rangle 
= h(y) - h(y^k) - \langle \nabla h(y^k), y - y^k \rangle 
= D_h(y, y^k).
\]

Thus, 
\[
D_h(y, u) + D_h(u, y^k) \leq D_h(y, y^k).
\]

By taking $k \to +\infty$, and using the fact that $h$ is essentially smooth, see condition $B_5$, and equality (5), we obtain $+\infty \leq 0$, which is a contradiction and therefore $y \in \mathcal{C}$.

Finally, by the continuity of $h$ and $\nabla h$, the condition (Iviii) is satisfied.

(b) $\varphi$-divergence proximal distances. Let $\varphi : \mathbb{R} \to \mathbb{R} \cup \{+\infty\}$ be an lower semicontinuous, convex, proper function such that $\text{dom } \varphi \subset \mathbb{R}_+$ and $\text{dom } \partial \varphi = \mathbb{R}_{++}$. We suppose in addition that $\varphi$ is $C^2$, strictly convex, and nonnegative on $\mathbb{R}_{++}$ with $\varphi(1) = \varphi'(1) = 0$. We denote by $\Phi$ the class of such kernels and by $\Phi_1$ the subclass of these kernels satisfying
\[
\varphi''(1) \left(1 - \frac{1}{t}\right) \leq \varphi'(t) \leq \varphi''(1) \log t \quad \forall t > 0.
\]

The other subclass of $\Phi$ of interest is denoted by $\Phi_2$, where the inequality above is replaced by
\[
\varphi''(1) \left(1 - \frac{1}{t}\right) \leq \varphi'(t) \leq \varphi''(1)(t - 1) \quad \forall t > 0.
\]

Examples of functions in $\Phi_1, \Phi_2$ are (see, e.g., [2, 26])
\[
\varphi_1(t) = t \log t - t + 1, \quad \text{dom } \varphi = [0, +\infty),
\]
\[
\varphi_2(t) = -\log t + t - 1, \quad \text{dom } \varphi = (0, +\infty),
\]
\[
\varphi_3(t) = 2(\sqrt{t} - 1)^2, \quad \text{dom } \varphi = [0, +\infty),
\]

Corresponding to the classe $\Phi_1$, we define a $\varphi$-divergence proximal distance
by
\[ d_\varphi(x, y) = \sum_{i=1}^{n} y_i \varphi \left( \frac{x_i}{y_i} \right). \]

For any \( \varphi \in \Phi \), since \( \text{argmin}\{ \varphi(t) : t \in \mathbb{R} \} = \{1\} \), \( \varphi \) is coercive and thus it follows that \( d_\varphi \in \mathcal{D}(\mathbb{C}) \), with \( \mathbb{C} = \mathbb{R}^{++} \).

Let \( \varphi \in \Phi_1 \) and define the regularized \( \varphi \)-divergence proximal distance (class \( \Phi_1 \)) by
\[ \tilde{d}_\varphi(x, y) := \sum_{i=1}^{n} y_i \varphi \left( \frac{x_i}{y_i} \right) + \frac{\sigma}{2} \|x - y\|^2. \]

where \( \sigma \) is a positive constant. Note also that \( \tilde{d}_\varphi \in \mathcal{D}(\mathbb{C}) \). Taking \( \varphi(t) = t - \log t - 1 \), we obtain
\[ \tilde{d}_\varphi(x, y) := \sum_{i=1}^{n} x_i - y_i - y_i \log \frac{x_i}{y_i} + (\sigma/2) \|x - y\|^2. \]

Taking
\[ \tilde{H}(x, y) = \sum_{j=1}^{n} x_j \log \frac{x_j}{y_j} + y_j - x_j + \frac{\sigma}{2} \|x - y\|^2 \]

and one has
\[ \langle c - b, \nabla_1 \tilde{d}_\varphi(b, a) \rangle \leq \tilde{H}(c, a) - \tilde{H}(c, b) - \gamma \tilde{H}(b, a), \]

see Auslender and Teboulle [4] (Subsection 2.3, Case a2), and therefore \( (\tilde{d}_\varphi, \tilde{H}) \in \mathcal{F}_+(\mathbb{R}_+^n) \). We note also that, defining
\[ h(x) := \sum_{j=1}^{n} x_j \log x_j + (\sigma/2) \|x\|^2 \]

and adopting the convention \( 0 \log 0 = 0 \), we have \( D_h(x, y) = \tilde{H} \) and thus \( \tilde{H} \) satisfies the condition \( (B_5) \). Therefore, as \( h \) is an essentially smooth Bregman function, we obtain that \( \tilde{H} \) satisfies the condition \( (Iviii) \).

(c) **Second order homogeneous proximal distances.** Let \( p \in \Phi_2 \), \( \varphi(t) = \mu p(t) + \frac{\nu}{2} (t - 1)^2 \) with \( \nu \geq \mu p''(1) > 0 \), and let the associated proximal distance be defined by
\[ d_\varphi(x, y) = \sum_{j=1}^{n} y_j^2 \varphi \left( \frac{x_j}{y_j} \right). \]

It is clear that, \( d_\varphi \in \mathcal{D}(\mathbb{R}^{n}_{++}) \) and from the key inequality (see formula (3.21) [2], Lemma 3.4) for any \( p \in \Phi_2 \) one has
\[ \langle c - b, \nabla_1 d_\varphi(b, a) \rangle \leq \bar{\eta}(\|c - a\|^2 - \|c - b\|^2 - \gamma \|b - a\|^2) \quad \forall a, b \in \mathbb{R}_+^n, \quad \forall c \in \mathbb{R}_+^n \]
where $\bar{\eta} = 2^{-1}(\nu + \mu \nu''(1))$. Therefore with

$$H(x, y) = \bar{\eta} \| x - y \|^2, \quad \gamma = \frac{\nu - \mu \nu''(1)}{\nu + \mu \nu''(1)}$$

it follows that $(d_\varphi, H) \in \mathcal{F}_+ (\mathcal{R}^n_+)$, also clearly the condition (Iviii) is satisfied.

The main result of the method will be when $(d, H) \in \mathcal{F}_+ (\mathcal{C})$ and the condition (Iviii) is satisfied.

4. An inexact proximal multiplier method with proximal distances

4.1. The Problem

We are interested in solving the following convex minimization problem with separable structure:

$$(CP) \min \{ f(x) + g(z) : Ax + Bz = b, \, x \in \bar{\mathcal{C}}, \, z \in \bar{\mathcal{K}} \},$$

where $\mathcal{C} \subset \mathbb{R}^n$ and $\mathcal{K} \subset \mathbb{R}^p$ are nonempty open convex sets, $\bar{\mathcal{C}}$ and $\bar{\mathcal{K}}$ denote the closure (in Euclidean topology) of $\mathcal{C}$ and $\mathcal{K}$ respectively, $f : \mathbb{R}^n \to (-\infty, +\infty]$ and $g : \mathbb{R}^p \to (-\infty, +\infty]$ are closed proper convex functions and $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{n \times p}$, $b \in \mathbb{R}^m$. Note that many convex programs can be formulated in the generic form (CP), see e.g. [13, 22].

The Lagrangian for (CP) is defined by $L : \mathbb{R}^n \times \mathbb{R}^p \times \mathbb{R}^m \to (-\infty, +\infty)$,

$$L(x, z, y) = (f + \delta_\mathcal{C})(x) + (g + \delta_\mathcal{K})(z) + \langle y, Ax + Bz - b \rangle,$$

where $\delta_X$ denotes the indicator function of a subset $X$, $\langle \cdot, \cdot \rangle$ denotes the canonical inner product and $y$ is the Lagrangian multiplier associated with the constraint $Ax + Bz = b$.

Let $(x^*, z^*) \in \mathbb{R}^n \times \mathbb{R}^p$ and $y^* \in \mathbb{R}^m$. In order that $(x^*, z^*)$ be an optimal solution of (CP) and $y^*$ be an optimal Lagrangian multiplier, it is necessary and sufficient that $(x^*, z^*, y^*)$ be a saddle point of the Lagrangian $L$ of (CP) (see [22], Theorem 28.3); i.e., for all $x \in \text{dom} f \cap \mathcal{C}$, $z \in \text{dom} g \cap \mathcal{K}$ and $y \in \mathbb{R}^m$, we have

$$L(x^*, z^*, y) \leq L(x^*, z^*, y^*) \leq L(x, z, y^*).$$

4.2. The (PMAPD) Algorithm

In the proposed algorithm we use the class of proximal distances $(d_0, H_0) \in \mathcal{F}_+ (\mathcal{C})$, $(d'_0, H'_0) \in \mathcal{F}_+ (\mathcal{K})$, satisfying the condition (Iviii) and given $\mu > 0, \mu' > 0$ we define the following functions:

$$d(x, y) = d_0(x, y) + (\mu/2) \| x - y \|^2, \quad (7)$$

$$H(x, y) = H_0(x, y) + (\mu/2) \| x - y \|^2, \quad (8)$$

$$d'(x, y) = d'_0(x, y) + (\mu'/2) \| x - y \|^2, \quad (9)$$

$$H'(x, y) = H'_0(x, y) + (\mu'/2) \| x - y \|^2. \quad (10)$$
It is easy to check that \((d, H) \in F_+(\bar{C})\) and \((d', H') \in F_+(\bar{K})\) (for the same value of \(\gamma\) and \(\gamma'\) respectively) and both satisfy the condition (Iviii).

The algorithm, which will be called Proximal Multiplier Algorithm with Proximal Distances (PMAPD) is as follows:

**(PMAPD) Algorithm**

**Step 0.** Choose two pairs \((d_0, H_0) \in F_+(\bar{C}), (d'_0, H'_0) \in F_+(\bar{K})\) satisfying the condition (Iviii) and define \((d, H), (d', H')\) given by (7)-(8) and (9)-(10) respectively. Take three sequences \(a_k \geq 0, b_k \geq 0\) and \(\lambda_k > 0\) and choose an arbitrary starting point \((x^0, z^0, y^0) \in C \times K \times IR^m\).

**Step 1.** For \(k = 0, 1, 2, \ldots\), calculate \(p^{k+1} \in IR^m\) by

\[
p^{k+1} = y^k + \lambda_k(Ax^k + Bz^k - b).
\]

**Step 2.** Find \((x^{k+1}, \nu^{k+1}) \in C \times IR^n\) and \((z^{k+1}, \xi^{k+1}) \in K \times IR^p\) such that

\[
\begin{align*}
\nu^{k+1} &\in \partial_a f^k(x^{k+1}), &\nu^{k+1} + \lambda_k^{-1} \nabla_1 f(x^{k+1}, x^k) &= 0, \\
\xi^{k+1} &\in \partial_b g^k(z^{k+1}), &\xi^{k+1} + \lambda_k^{-1} \nabla_1 g(z^{k+1}, z^k) &= 0.
\end{align*}
\]

where the functions \(f^k : IR^n \to (-\infty, +\infty]\) and \(g^k : IR^p \to (-\infty, +\infty]\) are defined by \(f^k(x) = f(x) + \langle p^{k+1}, Ax \rangle\) and \(g^k(z) = g(z) + \langle p^{k+1}, Bz \rangle\), respectively.

**Step 3.** Compute

\[
y^{k+1} = y^k + \lambda_k(Ax^{k+1} + Bz^{k+1} - b).
\]

**Stop criterium:** If \(x^{k+1} = x^k, z^{k+1} = z^k\) and \(y^{k+1} = y^k\) then stop. Otherwise to do \(k := k + 1\), and go to Step 1.

**Remark 1** If the stopping criterion is satisfied, then the (PMAPD) find an \((a_k + b_k)\)-solution of (CP). Of fact, if \(x^{k+1} = x^k, z^{k+1} = z^k\) and \(y^{k+1} = y^k\), from (12) and (13) we have

\[
0 \in \partial_a f^k(x^k) \quad \text{and} \quad 0 \in \partial_b g^k(z^k)
\]

and from (11) and (14), we have

\[
Ax^k + Bz^k = b \quad \text{and} \quad p^{k+1} = y^k
\]

from (15), we obtain

\[
\begin{align*}
f^k(x) &\geq f^k(x^k) - a_k \quad \forall x \in dom f, \\
g^k(z) &\geq g^k(z^k) - b_k \quad \forall z \in dom g,
\end{align*}
\]

adding and rearranging terms, using (16), we get

\[
f(x^k) + g(z^k) - (a_k + b_k) \leq f(x) + g(z) + \langle y^k, Ax + Bz - b \rangle
\]
then for all \( x \in \text{dom} f \cap \bar{C} \) and \( z \in \text{dom} g \cap \bar{K} \) such that \( Ax + Bz = b \), we obtain
\[
f(x^k) + g(z^k) - (a_k + b_k) \leq f(x) + g(z).
\]
Therefore
\[
f(x^k) + g(z^k) \leq \inf \{ f(x) + g(z) : Ax + Bz = b, x \in \bar{C}, z \in \bar{K} \} + (a_k + b_k).
\]
Thus, we obtain the result.

**Remark 2** As we are interested in the asymptotic convergence of the method, we assume that \((x^{k+1}, z^{k+1}, y^{k+1}) \neq (x^k, z^k, y^k)\), for all \( k \).

### 4.3. Global convergence

In this subsection, under appropriate assumptions, we prove that the iterations given by the algorithm are well defined and we establish the global convergence of the (PMAPD).

Throughout the paper we assume the following assumptions:

(H1) The problem (CP) has an optimal solution \((x^*, z^*)\) and a corresponding Lagrange multiplier \(y^*\).

(H2) There exist \( x \in \text{ri}(\text{dom} d(\cdot, v)) \cap \text{ri}(\text{dom} f) \) and \( z \in \text{ri}(\text{dom} d'(\cdot, v')) \cap \text{ri}(\text{dom} g) \) such that \( Ax + Bz = b \).

(H3) The sequences \( \{a_k\} \) and \( \{b_k\} \) are nonnegative and
\[
\sum_{k=0}^{\infty} (a_k + b_k) < \infty.
\]

(H4) Given the parameters \( \mu > 0, \mu' > 0 \), defined in (7) and (9) respectively, the sequence \( \{\lambda_k\} \) satisfies
\[
\eta < \lambda_k < \bar{c} - \eta \tag{17}
\]
where \( \eta \in (0, \bar{c}/2) \) with \( \bar{c} := \min \{ \sqrt{\gamma \mu}, \sqrt{\gamma' \mu'} \} \) and \( \gamma, \gamma' \) are positive constants related to \( d \) and \( d' \), respectively, in Definition 4, (iii).

**Remark 3** Assumption (H1) implies that the Lagrangian function \( L \) has a saddle point \((x^*, z^*, y^*)\). Assumption (H2) guaranteed the existence of an optimal dual Lagrange multiplier \( y^* \) associated with the constraint \( Ax + Bz = b \), and associate with Assumption (H1) ensure that the iterations given by the (PMAPD) are well defined. The above assumptions are not very strong and these has been used in previous researches, see [3, 9, 16]. Assumption (H3) is a natural condition when we work with inexact iterations. Assumption (H4) will be used to ensures the convergence of the method. Observe that the interval \((\eta, \bar{c} - \eta)\) depends of \( \mu \) and \( \mu' \) which are arbitrary.

**Theorem 4.1** Let \( d_0 \in \mathcal{D}(C) \) and \( d'_0 \in \mathcal{D}(K) \). Suppose that assumptions (H1) and (H2) are satisfied, then for any \((x^k, z^k, y^k) \in C \times K \times \mathbb{R}^m, \lambda_k > 0, \) exists \((x^{k+1}, z^{k+1}) \in C \times K \) satisfying (12) and (13).
Thus, there exists \( \bar{\xi} \)

Therefore the proof is completed.

From Definition 3, (ii), we have that \( \text{dom} \ (F_k) = \text{dom} \ f \cap \text{dom} \ d(\cdot, x^k) \neq \emptyset \). Define \( S_k = \arg \min_{x \in C} \{ F_k(x) \} = \arg \min_{x \in \mathbb{R}^n} \{ F_k(x) + \epsilon(x) \} \), where \( \epsilon \) denote the indicator function, we will prove that \( S_k \) is nonempty. Indeed, because \( f(\cdot), (A^T p^{k+1}, \cdot) \) and \( (1/\lambda_k)d(\cdot, x^k) \) are closed proper convex functions, then \( F_k \) is closed proper and convex too and from propositions 2.1 and 2.2, it is suffices to show that \( ((F_k + \epsilon)(y)) > 0, \forall y \neq 0 \).

Let \( y \neq 0 \), then by Proposition 2.3, we have that

\[
((F_k + \epsilon)0^+)(y) = (f0^+)(y) + ((A^T p^{k+1}, 0^+)(y) + (1/\lambda_k)(d(\cdot, x^k)0^+)(y) + (\epsilon0^+)(y).
\]

It is easy to prove that

\[
(f0^+)(y) > -\infty, \ (\epsilon0^+)(y) > -\infty, \ ((A^T p^{k+1}, 0^+)(y) = (A^T p^{k+1}, y).
\]

so we prove that \( (d(\cdot, x^k)0^+)(y) = +\infty \).

From Proposition 2.4, for \( \bar{x} \in \text{dom} \ d_0(\cdot, x^k) \), we have that

\[
(d(\cdot, x^k)0^+)(y) = \lim_{\lambda \to +\infty} \left( \frac{d_0(x, x^k) - d_0(\bar{x}, x^k)}{\lambda} \right) = \mu \frac{2}{\|y\|^2} \|\bar{x} - x^k, y\|.
\]

and since \( d_0(\cdot, x^k) \) convex function, we obtain that \( (d(\cdot, x^k)0^+)(y) = +\infty \) and therefore from (18)

\[
((F_k + \epsilon)0^+)(y) = +\infty > 0, \ \forall y \neq 0.
\]

Thus, there exists \( \bar{x} := x^{k+1} \in \mathbb{R}^m \) such that

\[
0 \in \partial \left( f(\cdot) + (A^T p^{k+1}, \cdot) + (1/\lambda_k)d(\cdot, x^k) + \epsilon(\cdot) \right)(x^{k+1}).
\]

Now by Assumption (H2) and Definition of \( d(\cdot, x^k) \), there exists \( x \in \text{ri} \text{dom} \ f \cap \text{ri} \text{dom} \ d(\cdot, x^k) \cap C \), then from Proposition 2.5, we have that

\[
0 \in \partial f(x^{k+1}) + A^T p^{k+1} + (1/\lambda_k) \partial d(x^{k+1}, x^k) + \partial \epsilon(x^{k+1}).
\]

From Definition 3, (ii), we have that \( \text{dom} \ \partial d(\cdot, x^k) = C \), then \( x^{k+1} \in C \).

As \( \partial f(x) \subseteq \partial \epsilon f(x) \) for all \( \epsilon \geq 0 \), then there exists \( x^{k+1} \in C \) and \( v^{k+1} \in \mathbb{R}^n \) satisfying (12).

For the existence of \( x^{k+1} \in K \) and \( \xi^{k+1} \in \mathbb{R}^p \) satisfying (13) the analysis is similar. Therefore the proof is completed.

The subsequent convergence analysis follows a line of argument similar to that given in [9].

**Lemma 4.2** ([9], Lemma 3.1) Let \( F : \mathbb{R}^m \to (-\infty, +\infty) \) a closed proper convex function, \( \tau > 0 \) and define:

\[
u^{k+1} = \arg \min_{\nu \in \mathbb{R}^m} \{ F(u) + (1/(2\tau))\|u - u^k\|^2 \}.
\]

Then for any integer \( k \geq 0 \),

\[2\tau|F(u^{k+1}) - F(u)| \leq \|u^k - u\|^2 - \|u^{k+1} - u\|^2 - \|u^{k+1} - u^k\|^2, \ \forall u \in \mathbb{R}^m.\]

12
We will also use the following useful notation

\[ \Delta_k(x, z) = H(x, x^k) - H(x, x^{k+1}) - \gamma H(x^{k+1}, x^k) + H'(z, z^k) - H'(z, z^{k+1}) - \gamma' H'(z^{k+1}, z^k) \]  

\[ (19) \]

**Lemma 4.3** Let \((d_0, H_0) \in \mathcal{F}(\mathcal{C}), (d_0', H_0') \in \mathcal{F}(\mathcal{K})\). Suppose that the assumptions (H1) and (H2) are satisfied. Then, for all \(x \in \text{dom} f \cap \mathcal{C}, z \in \text{dom} g \cap \mathcal{K}, y \in \mathbb{R}^m\) the following inequalities are satisfied:

1. \(\lambda_k \{ L(x^{k+1}, z^{k+1}, p^{k+1}) - L(x, z, p^{k+1}) \} \leq \Delta_k(x, z) + \lambda_k(a_k + b_k)\)
2. \(\lambda_k \{ L(x^k, z^k, y - L(x^k, z^k, p^{k+1}) \} \leq \| y^k - y \|^2 - \| y^{k+1} - y \|^2 - \| y^{k+1} - y \|^2\)
3. \(\lambda_k \{ L(x^{k+1}, z^{k+1}, y^{k+1}) - L(x^{k+1}, z^{k+1}, y^{k+1}) \} \leq \| y^k - y \|^2 - \| y^{k+1} - y \|^2 - \| y^{k+1} - y \|^2\).

**Proof.** (i) Let \(x \in \text{dom} f \cap \mathcal{C}, z \in \text{dom} g \cap \mathcal{K}, y \in \mathbb{R}^m\) from definition of \(L\), it is clear that

\[ L(x^{k+1}, z^{k+1}, p^{k+1}) - L(x, z, p^{k+1}) = (f^k(x^{k+1}) - f^k(x)) + (g^k(z^{k+1}) - g^k(z)). \]  

(20)

Since \(y^{k+1} \in \partial_a f^k(x^{k+1})\), then \(f^k(x) \geq f^k(x^{k+1}) + \langle v^{k+1}, x - x^{k+1} \rangle - a_k\), then from (12) and from Definition 4, (Iii), we obtain

\[ \lambda_k(f^k(x^{k+1}) - f^k(x)) \leq \langle \nabla_1 d(x^{k+1}, x^k), x - x^{k+1} \rangle + \lambda_k a_k \leq H(x, x^k) - H(x, x^{k+1}) - \gamma H(x^{k+1}, x^k) + \lambda_k a_k. \]  

(21)

Analogously, since \(\xi^{k+1} \in \partial_b g^k(z^{k+1})\), we have \(g^k(z) \geq g^k(z^{k+1}) + \langle \xi^{k+1}, z - z^{k+1} \rangle - b_k\), then from (13) and from Definition 4, (Iii), we obtain

\[ \lambda_k(g^k(z^{k+1}) - g^k(z)) \leq \nabla_1 d'(z^{k+1}, z^k), z - z^{k+1} + \lambda_k b_k \leq H'(z, z^k) - H'(z, z^{k+1}) - \gamma' H'(z^{k+1}, z^k) + \lambda_k b_k, \]  

(22)

by adding (21) and (22), and from (20) and the notation in (19), we obtain

\[ \lambda_k \{ L(x^{k+1}, z^{k+1}, p^{k+1}) - L(x, z, p^{k+1}) \} \leq \Delta_k(x, z) + \lambda_k(a_k + b_k). \]

To prove (ii) and (iii) note that Steps 1 and 3 of (PMAK) can be written equivalently as:

\[ p^{k+1} = \arg \min_{y \in \mathbb{R}^m} \{ -L(x^k, z^k, y) + (1/2\lambda_k)\| y - y^k \|^2 \} \]

\[ y^{k+1} = \arg \min_{y \in \mathbb{R}^m} \{ -L(x^{k+1}, z^{k+1}, y) + (1/2\lambda_k)\| y - y^k \|^2 \} \]

Then, using Lemma 4.2, twice with \(\tau = \lambda_k, F(y) = -L(x^k, z^k, y)\) and \(F(y) = -L(x^{k+1}, z^{k+1}, y)\) respectively, the first and second equations above respectively yield the desired inequalities (ii) and (iii).

**Remark 4** Throughout the rest of this paper, we denote \(w^k = (x^k, z^k, y^k), w^* = (x^*, z^*, y^*)\), \(w = (x, z, y), s = (l, q, r) \in \mathbb{R}^n \times \mathbb{R}^p \times \mathbb{R}^m\) and define the function \(\hat{H} : X \times X \rightarrow \mathbb{R}_+ \cup \{+\infty\}\) by

\[ \hat{H}(w, s) = \hat{H}(x, z, y, (l, q, r)) = H(x, l) + H'(z, q) + (1/2\| y - r \|^2, \]  

(23)

where \(X = \mathbb{R}^n \times \mathbb{R}^p \times \mathbb{R}^m, H\) and \(H'\) are defined in (8) and (10) respectively.
Then, by adding (28) and (31) and from (23), we obtain

\[
\hat{H}(w^*, w^{k+1}) \leq \hat{H}(w^*, w^k) - \gamma H_0(x^{k+1}, x^k) + (1/2) (\gamma \mu - 4\lambda_k^2 \|A\|^2) \|x^{k+1} - x^k\|^2 + \\
- \langle \gamma H'(0, z^k) + (1/2) (\gamma' \mu' - 4\lambda_k^2 \|B\|^2) \|z^{k+1} - z^k\|^2 \rangle + \\
- (1/2) (\|p^{k+1} - y^{k+1}\|^2 + \|p^{k+1} - y^k\|^2) + \lambda_k (a_k + b_k),
\]

(24)

where \( w^* = (x^*, z^*, y^*) \). In particular, we have, for all \( k \),

\[
\hat{H}(w^*, w^{k+1}) \leq \hat{H}(w^*, w^k) + \lambda_k (a_k + b_k).
\]

(25)

**Proof.** Taking \((x, z) = (x^*, z^*)\) in Lemma 4.3, (i), we obtain

\[
\lambda_k (L(x^{k+1}, z^{k+1}, p^{k+1}) - L(x^*, z^*, p^{k+1})) \leq H(x^*, x^k) - H(x^*, x^{k+1}) + H'(z^*, z^k) + \\
- H'(z^*, z^{k+1}) - \gamma H(x^{k+1}, x^k) + \\
+ \gamma' H'(z^{k+1}, z^k) + \lambda_k (a_k + b_k).
\]

(26)

Since \((x^*, z^*, y^*)\) is a saddle point of \( L \), we obtain from (6)

\[
\lambda_k (L(x^*, z^*, p^{k+1}) - L(x^{k+1}, z^{k+1}, y^*)) \leq 0.
\]

(27)

By adding (26) and (27) and rearranging terms, we get

\[
H(x^*, x^{k+1}) + H'(z^*, z^{k+1}) \leq H(x^*, x^k) + H'(z^*, z^k) - \gamma H(x^{k+1}, x^k) + \\
+ \gamma' H'(z^{k+1}, z^k) + \\
- \lambda_k \langle y^{k+1} - y^*, A x^{k+1} + B z^{k+1} - b \rangle + \lambda_k (a_k + b_k).
\]

(28)

Now, using Lemma 4.3, (ii), with \( y := y^{k+1} \) and \( y := y^* \) for (iii), we obtain, respectively,

\[
2\lambda_k (L(x^k, z^k, y^{k+1}) - L(x^k, z^k, p^{k+1})) \leq \|y^k - y^{k+1}\|^2 - \|p^{k+1} - y^{k+1}\|^2 - \|p^{k+1} - y^k\|^2
\]

(29)

\[
2\lambda_k (L(x^{k+1}, z^{k+1}, y^*) - L(x^{k+1}, z^{k+1}, y^{k+1})) \leq \|y^k - y^*\|^2 - \|y^{k+1} - y^*\|^2 - \|y^{k+1} - y^k\|^2
\]

(30)

adding (29) and (30) and rearranging terms, we get

\[
(1/2) \|y^{k+1} - y^*\|^2 \leq (1/2) \|y^k - y^*\|^2 - (1/2) \|p^{k+1} - y^{k+1}\|^2 - \|p^{k+1} - y^k\|^2 \]

\[
- \lambda_k \langle y^k - y^{k+1}, A x^{k+1} + B z^{k+1} - b \rangle + \\
+ \langle y^{k+1} - p^{k+1}, A x^k + B z^k - b \rangle.
\]

(31)

Then, by adding (28) and (31) and from (23), we obtain

\[
\hat{H}(w^*, w^{k+1}) \leq \hat{H}(w^*, w^k) - \gamma H(x^{k+1}, x^k) + \gamma' H'(z^{k+1}, z^k) + \\
- (1/2) (\|p^{k+1} - y^{k+1}\|^2 + \|p^{k+1} - y^k\|^2) + \lambda_k (a_k + b_k) + \\
+ \lambda_k \langle y^{k+1} - p^{k+1}, A (x^{k+1} - x^k) + B (z^{k+1} - z^k) \rangle
\]

(32)

\[
= \hat{H}(w^*, w^k) - \gamma H(x^{k+1}, x^k) + \gamma' H'(z^{k+1}, z^k) + \\
- (1/2) (\|p^{k+1} - y^{k+1}\|^2 + \|p^{k+1} - y^k\|^2) + \\
+ \lambda_k \|A (x^{k+1} - x^k) + B (z^{k+1} - z^k)\|^2 + \lambda_k (a_k + b_k),
\]
where the last equality follows from (11) and (14).

Using, in (32), the inequality
\[ \left\| A(x^{k+1} - x^k) + B(z^{k+1} - z^k) \right\|^2 \leq 2 \left( \|A\|^2 \|x^{k+1} - x^k\|^2 + \|B\|^2 \|z^{k+1} - z^k\|^2 \right), \]
and also,
\[
\begin{align*}
H(x^{k+1}, x^k) &= H_0(x^{k+1}, x^k) + (\mu / 2)\|x^{k+1} - x^k\|^2, \\
H'(z^{k+1}, z^k) &= H'_0(z^{k+1}, z^k) + (\mu' / 2)\|z^{k+1} - z^k\|^2,
\end{align*}
\]
we obtain
\[
\hat{H}(w^*, w^{k+1}) \leq \hat{H}(w^*, w^k) - [\gamma H_0(x^{k+1}, x^k) + (1/2)(\gamma \mu - 4\lambda_k^2 \|A\|^2)\|x^{k+1} - x^k\|^2] +
\begin{align*}
&- (\gamma' H'_0(z^{k+1}, z^k) + (1/2)(\gamma' \mu' - 4\lambda_k^2 \|B\|^2)\|z^{k+1} - z^k\|^2) +
&- (1/2) \left( \|y^{k+1} - y^k\|^2 + \|p^{k+1} - y^k\|^2 \right) + \lambda_k (a_k + b_k).
\end{align*}
\]

Then, the inequality (25) follows immediately from (24) and Assumption (H4). \(\square\)

**Lemma 4.5** ([21], Lemma 2) Let \(\{\alpha_k\}\) and \(\{\beta_k\}\) be nonnegative sequences such that \(\alpha_{k+1} \leq \alpha_k + \beta_k\), for all \(k\) and \(\sum_{k=0}^{\infty} \beta_k < +\infty\). Then \(\{\alpha_k\}\) is convergent.

**Proposition 4.6** Let \((d_0, H_0) \in \mathcal{F}_+(\mathcal{C}), (d'_0, H'_0) \in \mathcal{F}_+(\mathcal{K})\) satisfying the condition (Iviii). Suppose that assumptions (H1), (H2), (H3) and (H4) are satisfied. Let \(\{w_k\}\) be a sequence generated by the (PMAPD) algorithm, then \(\{w^k\}\) is bounded and every accumulation point of \(\{w^k\}\) is a saddle point of the Lagrangian \(L\).

**Proof.** First, note that Assumption (H3) together with Assumption (H4) ensures that
\[
\sum_{k=0}^{\infty} \lambda_k (a_k + b_k) < +\infty. \tag{33}
\]

Then, from (25), we have
\[ w^k \in L_{\hat{H}}(w^*, \bar{\alpha}) := \{ w : \hat{H}(w^*, w) \leq \bar{\alpha} \}, \text{ for all } k, \]
where \(\bar{\alpha} = \hat{H}(w^*, w^0) + \sum_{k=0}^{\infty} \lambda_k (a_k + b_k)\).

This implies that \(\{w^k\}\) is bounded because of condition (Iv) in Definition 4 for \(H\) and \(H'\).

Now, let \((x^*, z^*)\) be an optimal solution of (CP), let \(y^*\) be a corresponding Lagrange multiplier, and let \(w^* = (x^*, z^*, y^*)\).

Then, from (25), (33) and Lemma 4.5, we obtain that \(\{\hat{H}(w^*, w^k)\}\) is convergent, i.e., there exists \(\beta \geq 0\) such that
\[
\lim_{k \to +\infty} \hat{H}(w^*, w^k) = \beta, \tag{34}
\]
Taking limit in the inequality of Lemma (24), from Assumption (H3) and rear-
Indeed, since
\[ \limsup_{k \to +\infty} (\gamma H_0(x^{k+1}, x^k) + \frac{1}{2}(\gamma \mu - 4\lambda^2_k ||A||^2) ||x^{k+1} - x^k||^2 + \frac{1}{2}(\gamma \mu' - 4\lambda^2_k ||B||^2) ||z^{k+1} - z^k||^2 + \gamma' H'_0(z^{k+1}, z^k) + \frac{1}{2}(||p^{k+1} - y^{k+1}||^2 + ||p^{k+1} - y^k||^2) \) \leq 0. \] (35)

It then follows from (34) and assumption (H4) that
\[ H_0(x^{k+1}, x^k) \to 0, \|x^{k+1} - x^k\| \to 0 \]
\[ H'_0(z^{k+1}, z^k) \to 0, \|z^{k+1} - z^k\| \to 0 \]
\[ ||p^{k+1} - y^{k+1}|| \to 0, ||p^{k+1} - y^k|| \to 0. \] (36)

Now, let \( \bar{w} = (\bar{x}, \bar{z}, \bar{y}) \) be a cluster point of \( \{w^k\} \), and let \( \{w^k\}_{k \in K} \) a subsequence converging to \( \bar{w} \). Using Lemma 4.3, (i), for all \( x \in \text{dom} f \cap \bar{C} \) and \( z \in \text{dom} g \cap \bar{K} \), we have
\[ \lambda_k \{ L(x^{k+1}, z^{k+1}, p^{k+1}) - L(x, z, p^{k+1}) \} \leq \Delta_k(x, z) + \lambda_k(a_k + b_k). \] (37)

Taking the limit over the appropriate subsequences on both sides of (46), using (36) and the Assumptions (H3), (H4), and condition (Iviii) for \( H \) and \( H' \), we obtain
\[ L(\bar{x}, \bar{z}, \bar{y}) - L(x, z, \bar{y}) \leq 0, \] (38)
\[ L(\bar{x}, \bar{z}, y) - L(\bar{x}, \bar{z}, \bar{y}) \leq 0. \] (39)

From (38) and (39), we obtain that, for all \( x \in \text{dom} f \cap \bar{C}, z \in \text{dom} g \cap \bar{K}, y \in \mathbb{R}^m \),
\[ L(\bar{x}, \bar{z}, y) \leq L(\bar{x}, \bar{z}, \bar{y}) \leq L(x, z, \bar{y}). \]

Therefore, \( \bar{w} \) is a saddle point of \( L \).

From the above propositions, we obtain the following convergence theorem for the (PMAPD).

**Theorem 4.7** Let \( (d_0, H_0) \in \mathcal{F}_+(\bar{C}), (d'_0, H'_0) \in \mathcal{F}_+(\bar{K}) \) satisfying the condition (Iviii). Suppose that the Assumptions (H1), (H2), (H3) and (H4) are satisfied and let \( \{(x^k, z^k, y^k)\} \) be the sequence generated by the (PMAPD), then the sequence \( \{(x^k, z^k, y^k)\} \) globally converges to \( (x^*, z^*, y^*) \), with \( (x^*, z^*) \) optimal for (CP) and \( y^* \) be a corresponding Lagrange multiplier.

**Proof.** From Proposition 4.6, \( \{w^k\} = \{(x^k, z^k, y^k)\} \) is bounded and any cluster point \( \bar{w} \) is a saddle point of \( L \).

Let \( \{w^k\}_{k \in K} \) be a subsequence which converges to \( \bar{w} \), then \( (\bar{x}, \bar{z}) \) is an optimal solution of (CP) and \( \bar{y} \) be a corresponding Lagrange multiplier (see [22], Theorem 28.3). Then, it is suffices to prove that \( \{w^k\} \) converges to \( \bar{w} \).

Indeed, since
\[ \lim_{k \to +\infty, k \in K} x^k = \bar{x}, \quad \lim_{k \to +\infty, k \in K} z^k = \bar{z}, \quad \lim_{k \to +\infty, k \in K} y^k = \bar{y}. \]

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from Definition 4, (Ivii), we have that
\[
\lim_{k \to +\infty, k \in K} H(\bar{x}, x^k) = 0, \quad \lim_{k \to +\infty, k \in K} H'(\bar{z}, z^k) = 0, \quad \lim_{k \to +\infty, k \in K} \frac{1}{2}\|y^k - \bar{y}\|^2 = 0
\]
then, taking \( w = \bar{w} \) and \( s = w^k \) in (23), we have
\[
\lim_{k \to +\infty, k \in K} \hat{H}(\bar{w}, w^k) = 0, \tag{40}
\]
From (25) substituting \( w^* \) by \( \bar{w} \) we obtain
\[
0 \leq \hat{H}(\bar{w}, w^{k+1}) \leq \hat{H}(\bar{w}, w^k) + \lambda_k(a_k + b_k), \quad \text{for all } k,
\]
Then, from Assumptions (H3), (H4) and Lemma 4.5 we have that \( \hat{H}(\bar{w}, w^k) \) converges and as there exists a subsequence which converges to zero, (see (40)), then all the sequence converges, that is,
\[
\lim_{k \to +\infty} \hat{H}(\bar{w}, w^k) = 0.
\]
Finally, from (23) and Definition 4, (Ivi), for \( H \) and \( H' \), we obtain that
\[
\lim_{k \to +\infty} w^k = \bar{w}.
\]
Thus, we obtain the result. \( \square \)

4.4. Convergence for a general case

In the previous section we analyzed the convergence of the algorithm (PMAPD) when \((d_0, H_0) \in \mathcal{F}_+(\bar{C}), (d'_0, H'_0) \in \mathcal{F}_+(\bar{K})\), in particular when the proximal distances satisfy the condition (Iii) of Definition 4, i.e.,
\[
\langle c - b, \nabla_1 d(b, a) \rangle \leq H(c, a) - H(c, b) - \gamma H(b, a), \quad \text{with } \gamma \in (0, 1],
\]
\[
\langle c - b, \nabla_1 d'(b, a) \rangle \leq H'(c, a) - H'(c, b) - \gamma' H'(b, a), \quad \text{with } \gamma' \in (0, 1].
\]
The above conditions are satisfied by the class of Bregman distances, second order homogeneous distances and for some \( \varphi \)-divergences distances. However, it is well known that all \( \varphi \)-divergences distance satisfy the above inequalities when \( \gamma = 0 \) and \( \gamma' = 0 \) that is,
\[
\text{(Iii)' : } \langle c - b, \nabla_1 d(b, a) \rangle \leq H(c, a) - H(c, b),
\]
see Teboulle [26], Lemma 4.1, (ii).
In this subsection we analyze the convergence of the algorithm (PMAPD) substituting in Definition 4 the condition (Iii) by (Iii)'. We also replace the assumption
(H4) by the following:

\[
\begin{align*}
\text{(H4)'} : & \quad \kappa < \lambda_k < \bar{\lambda} \\
& \quad \sum_{k=0}^{\infty} \|x^{k+1} - x^k\|^2 < +\infty \\
& \quad \sum_{k=0}^{\infty} \|z^{k+1} - z^k\|^2 < +\infty
\end{align*}
\]

where \( \kappa \) and \( \bar{\lambda} \) are positive constants.

Observe that, under the new assumptions, Theorem 4.1, Lemma 4.2, Lemma 4.3 (with \( \Delta_k(x, z) = H(x, x^k) - H(x, x^{k+1}) + H'(z, z^k) - H'(z, z^{k+1}) \)) continue to be true but Proposition 4.4 becomes

**Proposition 4.8** Let \((d_0, H_0) \in F(\mathcal{C}), (d_0', H_0') \in F(\mathcal{K})\). Suppose that Assumptions (H1), (H2) are satisfied. Let \(\{w^k\}\) and \(\{p^k\}\) be sequences generated by the (PAMAPD); let \((x^*, z^*)\) be an optimal solution of \((CP)\), and let \(y^*\) be a corresponding Lagrange multiplier, then we have, for each \(k\),

\[
\hat{H}(w^*, w^{k+1}) \leq \hat{H}(w^*, w^k) - (1/2)(\|p^{k+1} - y^{k+1}\|^2 + \|p^k - y^k\|^2) + 2\lambda_k^2(\|A\|^2\|x^{k+1} - x^k\|^2 + \|B\|^2\|z^{k+1} - z^k\|^2) + \lambda_k(a_k + b_k),
\]

where \(w^* = (x^*, z^*, y^*)\). In particular, we have, for all \(k\),

\[
\hat{H}(w^*, w^{k+1}) \leq \hat{H}(w^*, w^k) + 2\lambda_k^2(\|A\|^2\|x^{k+1} - x^k\|^2 + \|B\|^2\|z^{k+1} - z^k\|^2) + \lambda_k(a_k + b_k). \tag{41}
\]

**Proof.** Proceeding analogously as the proof of Proposition 4.4, using Lemma 4.3 with \(\Delta_k(x, z) = H(x, x^k) - H(x, x^{k+1}) + H'(z, z^k) - H'(z, z^{k+1})\), we obtain the result.

Then, we obtain the following result

**Proposition 4.9** Let \((d_0, H_0) \in F(\mathcal{C}), (d_0', H_0') \in F(\mathcal{K})\) (substituting (Iii) by (Iii)') satisfying the condition (Iviii). Suppose that the Assumptions (H1), (H2), (H3) and (H4)' are satisfied. Let \(\{w^k\}\) be a sequence generated by the (PAMAPD) algorithm, then \(\{w^k\}\) is bounded and every accumulation point of \(\{w^k\}\) is a saddle point of the Lagrangian \(L\).

**Proof.** The proof is analogous as the proof of Proposition 4.6. First, note that Assumption (H3) together with Assumption (H4)' ensures that

\[
\sum_{k=0}^{\infty} 2\lambda_k^2(\|A\|^2\|x^{k+1} - x^k\|^2 + \|B\|^2\|z^{k+1} - z^k\|^2) + \lambda_k(a_k + b_k) < +\infty. \tag{42}
\]

Then, from (41), we have

\[
w^k \in L_{\hat{H}}(w^*, \bar{\alpha}) := \{w : \hat{H}(w^*, w) \leq \bar{\alpha}\}, \text{ for all } k,
\]

where

\[
\bar{\alpha} = \hat{H}(w^*, w^0) + \sum_{k=0}^{+\infty} 2\lambda_k^2(\|A\|^2\|x^{k+1} - x^k\|^2 + \|B\|^2\|z^{k+1} - z^k\|^2) + \lambda_k(a_k + b_k).
\]
This implies that \( \{w^k\} \) is bounded due to condition (Iiv) in Definition 4 for \( H \) and \( H' \).

Now, let \((x^*, z^*)\) be an optimal solution of (CP), let \( y^* \) be a corresponding Lagrange multiplier, and let \( w^* = (x^*, z^*, y^*) \).

Then, from (41), (42) and Lemma 4.5, we obtain that \( \{\hat{H}(w^*, w^k)\} \) is convergent, i.e., there exists \( \beta \geq 0 \) such that

\[
\lim_{k \to +\infty} \hat{H}(w^*, w^k) = \beta.
\]  

Taking limsup in the first inequality of Proposition 4.8, we obtain

\[
\limsup_{k \to +\infty} \frac{1}{2}(\|p^{k+1} - y^{k+1}\|^2 + \|p^{k+1} - y^k\|^2) - 2\lambda_k^2(\|A\|^2\|x^{k+1} - x^k\|^2 + \|B\|^2\|z^{k+1} - z^k\|^2)
- \lambda_k(a_k + b_k) \leq 0,
\]

then from Assumptions (H3) and (H4)', we obtain

\[
\|x^{k+1} - x^k\| \to 0
\]
\[
\|z^{k+1} - z^k\| \to 0
\]
\[
\|p^{k+1} - y^{k+1}\| \to 0
\]
\[
\|p^{k+1} - y^k\| \to 0.
\]

Now, let \( \bar{w} = (\bar{x}, \bar{z}, \bar{y}) \) be a cluster point of \( \{w^k\} \), and let \( \{w^k\}_{k\in K} \) be a subsequence converging to \( \bar{w} \). Using Lemma 4.3, (i), for all \( x \in dom f \cap \bar{C} \) and \( z \in dom g \cap \bar{K} \), we have

\[
\lambda_k \{L(x^{k+1}, z^{k+1}, p^{k+1}) - L(x, z, p^{k+1})\} \leq \Delta_k(x, z) + \lambda_k(a_k + b_k).
\]

Taking the limit over the appropriate subsequences on both sides of (46), using (45) and the Assumptions (H3), (H4)', and condition (Iviii) for \( H \) and \( H' \), we obtain

\[
L(\bar{x}, \bar{z}, \bar{y}) - L(x, z, \bar{y}) \leq 0,
\]

since \( \lambda_k \) is bounded below by \( \kappa \).

Similarly, by taking the limit, over the appropriate subsequences, on both sides of the inequality in Lemma 4.3, (ii), we have that, for all \( y \in \mathbb{R}^m \),

\[
L(\bar{x}, \bar{z}, y) - L(x, \bar{z}, \bar{y}) \leq 0.
\]

From (47) and (48), we obtain that, for all \( x \in dom f \cap \bar{C}, z \in dom g \cap \bar{K}, y \in \mathbb{R}^m \),

\[
L(\bar{x}, \bar{z}, y) \leq L(\bar{x}, \bar{z}, \bar{y}) \leq L(x, z, \bar{y}).
\]

Therefore, \( \bar{w} \) is a saddle point of \( L \).

Finally, proceeding analogously as the proof of Theorem 4.7, using the result of Proposition 4.9, we have the following main result:

**Theorem 4.10** Let \((d_0, H_0) \in F_+^{\ast}(\bar{C}), (d_0', H_0') \in F_+^{\ast}(\bar{K})\) (substituting (Iii) by (Iii)'), satisfying the condition (Iviii). Suppose that the Assumptions
(H1), (H2), (H3) and (H4) are satisfied and let \( \{ (x^k, z^k, y^k) \} \) be the sequence generated by the (PMAPD), then the sequence \( \{ (x^k, z^k, y^k) \} \) globally convergences to \((x^*, z^*, y^*)\), with \((x^*, z^*)\) optimal for \( (CP) \) and \( y^* \) be a corresponding Lagrange multiplier.

Conclusions and future researches

In this article, we have proposed an inexact proximal multiplier method using regularized proximal distances called (PMAPD) for solving convex minimization problems with a separable structure. This method is an extension of the (PCPM) and (NPCPMM) methods given by Chen-Teboulle and Kyono-Fukushima respectively, and includes the class of regularized \( \varphi \)–divergence distances. Note also that the (EPDM) is a particular case of the our method when we consider exact iterations and we use the regularized log-quadratic distance. We have established, under standard assumptions, that the iterations generated by the method are well defined and the sequence converges to an optimal solution of the problem.

A future research may include to find a variant of the (PMAPD) method to obtain superlinear rate of convergence, as also, to perform computational experiments and comparison with other methods in the literature. The extension of the (PMAPD) to solve more general problems, such as, quasiconvex optimization and variational inequalities are desirable.

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